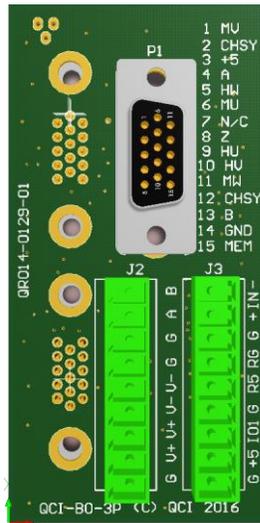


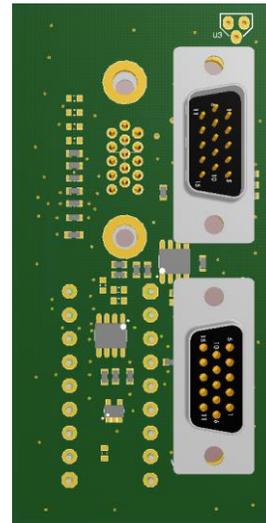
3-Phase Breakout Module QCI-BO-3P and QCI-BO-3P3

The QCI-BO-3P and QCI-BO-3P3 breakout modules enable SilverSterling S2 series controllers and SilverSterling S3 series controllers, respectively, to drive 3-phase motors with single-ended encoder and hall effect devices. The breakout board includes a differential amplifier with a X3 gain and can be ordered to accept a 0 to +10V or $\pm 10V$ analog input to scale down to 0 to 3.3V.

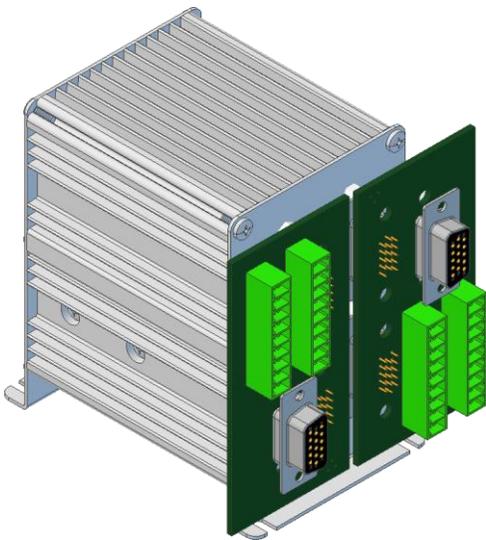
SilverSterling S2 controllers require software revision 23-22.
 SilverSterling S3 controllers require software revision 33-21.



Front view of QCI-BO-3Px



Back view of QCI-BO-3Px

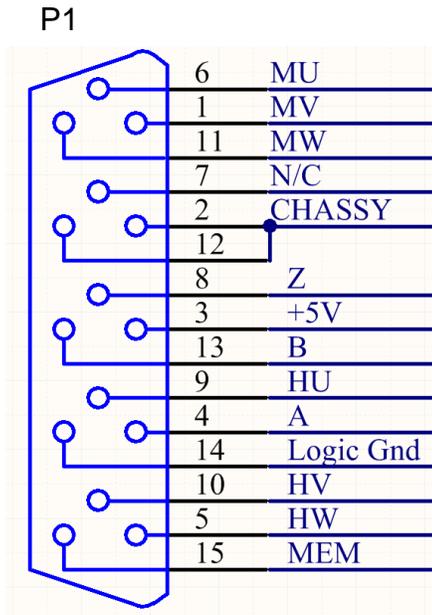


QCI-S2-X2-IG with two QCI-BO-3P Breakouts

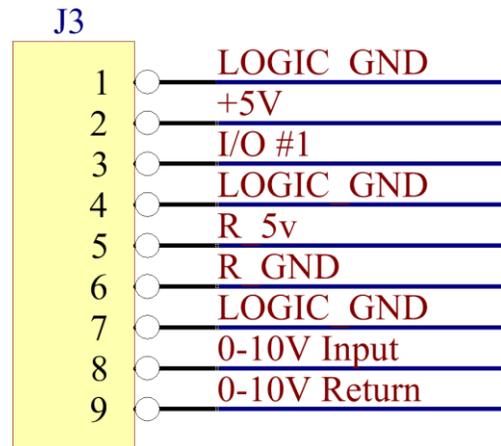
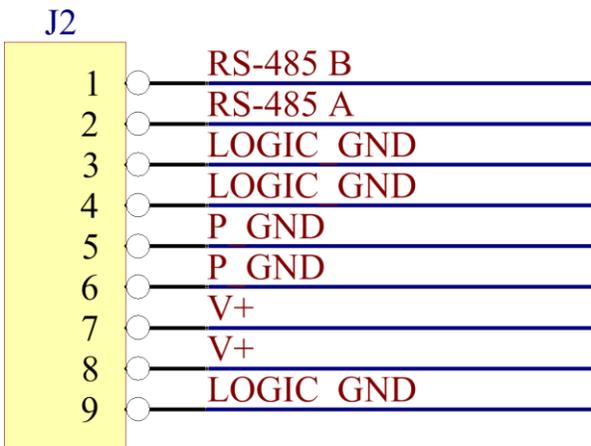


QCI-S3-IG with QCI-BO-3P3 Breakout

Connector Descriptions



| Pin | Signal Description |
|-----|-----------------------------|
| 1 | Motor Phase V |
| 2 | CHASSY |
| 3 | +5v Supply |
| 4 | Encoder A |
| 5 | Hall Sense Phase W |
| 6 | Motor Phase U |
| 7 | No Connect |
| 8 | Encoder Z |
| 9 | Hall Sense Phase U |
| 10 | Hall Sense Phase V |
| 11 | Motor Phase W |
| 12 | CHASSY |
| 13 | Encoder B |
| 14 | Logic Ground |
| 15 | Motor Memory; if available. |



Special Builds

QCI-BO-3PS0081 & QCI-BO-3P3S0081 bring out CAN signals to J3 connector:

- CAN High is brought out to Pin 5 on J3. Labeled as R5 in silkscreen.
- CAN Low is brought out to Pin 6 on J3. Labeled as RG in silkscreen.
- CAN Ground is brought out to Pins 1, 3, and 7. Labeled as G in silkscreen.